Simplified Shear Solution for Determination of the Shear Stress Distribution in a Composite Panel from the Applied Shear Resultant

Brett A. Bednarcyk¹ NASA Glenn Research Center, Cleveland, OH, 44135

Jacob Aboudi² Tel Aviv University, Ramat-Aviv, Israel 69978

and

Phillip W. Yarrington³ and Craig S. Collier⁴ Collier Research Corp., Hampton, VA

The "simplified shear solution" method is presented for approximating the throughthickness shear stress distribution within a composite laminate or panel based on laminated beam theory. The method does not consider the solution of a particular boundary value problem; rather it requires only knowledge of the global shear loading, geometry, and material properties of the laminate or panel. It is thus analogous to lamination theory in that ply level stresses can be efficiently determined from global load resultants (as determined, for instance, by finite element analysis) at a given location in a structure and used to evaluate the margin of safety on a ply by ply basis. The simplified shear solution stress distribution is zero at free surfaces, continuous at ply boundaries, and integrates to the applied shear load. Comparisons to existing theories are made for a variety of laminates, and design examples are provided illustrating the use of the method for determining through-thickness shear stress margins in several types of composite panels and in the context of a finite element structural analysis.

I. Introduction

I T is known that by employing lamination theory, one can determine the in-plane stress distribution in each layer of a laminate from the knowledge of the applied force and moment resultants. This information enables determination of ply-by-ply margins for the laminate, which are needed for design and sizing. The distributions of the interlaminar shear stresses in each layer from the applied shear resultants are not readily available from the standard lamination theory equations. These stresses are also needed to enable design and sizing of laminates subjected to global shear loads. The present report provides an analytical method, based on laminated beam theory with shear loading, for determining the interlaminar shear stress distribution in a laminate from a given applied shear resultant. It should be emphasized that the classical or the higher-order (e.g., first-order shear deformable) plate theory cannot be employed to determine the correct interlaminar shear stress distribution through the laminate thickness from the knowledge of the force, moment, and shear resultants. Indeed, the classical plate theory provides identically zero interlaminar shear stresses, whereas the higher-order plate theories provide piece-wise profiles that are discontinuous at the ply interfaces. It should also be noted that the simple shear solution provided herein does not involve the solution of a particular boundary value problem. Rather, it is only assumed that the force, moment, and shear resultants are known at a particular location in the laminate, and the solution is independent of the source

¹ Materials Research Engineer, 21000 Brookpark Rd., 49-7, AIAA Senior Member, Brett.A.Bednarcyk@nasa.gov

² Professor, School of Mechanical Engineering, Aboudi@eng.tau.ac.il

³ Senior Research Engineer, AIAA Member, Phil. Yarrington@hypersizer.com

⁴ Senior Research Engineer, AIAA Senior Member, Craig.Collier@hypersizer.com

of these known resultant quantities. Conversely, in order to obtain the interlaminar shear distribution via integration of the differential equations of equilibrium, the solution of a boundary value problem would be required to determine the variation of the stress fields in each ply.

The presented theory has been validated for laminates with one to five layers composed of both isotropic and anisotropic materials by comparison to approximate methods (HOTFMG¹, HyperSizer Joints²) and an exact plate solution³. Finally, the theory is implemented for the practical analysis of composite stiffened panels in the HyperSizer software⁴. Results, including predicted margins of safety, are given for a graphite/epoxy laminate, a honeycomb sandwich panel, an I-stiffened panel, and laminate components of a pressure shell structure.

II. Formulation

We seek to determine the distribution of the shear stress in a laminate given the global applied shear resultant, Q. Consider a laminate (Fig. 1) with an applied shear force P consisting of N layers, with the layer number denoted by k. Note that the positive directionality of P is motivated by that which causes a positive internal shear stress (see Appendix B). Following the concept of a composite beam⁵, the actual laminate cross-section is replaced with an effective cross-section. As shown in Fig. 2, the original width of each layer (b) is transformed to $b n_k$, where,

$$n_k = \frac{E_x^k}{\overline{E}_x} \tag{1}$$

 E_x^k is the Young's modulus of layer k in the x-direction, and \overline{E}_x is the average Young's modulus of the laminate in the x-direction. \overline{E}_x serves only as a normalization factor which allows the ply stiffnesses to be scaled with respect to each other. Alternatively, the Young's modulus of one particular ply may be used. Note that in bending, under a plane strain condition, where, $\varepsilon_y = 0$, E_x^k should be modified to $E_x^k \rightarrow E_x^k / [1 - v_{xy}^k v_{yx}^k]$ (see Appendix A). The neutral axis for the laminate is located at the centroid of the transformed laminate cross-section and is given (with respect to the laminate midplane coordinate system) by,

$$z^{*} = \frac{\sum_{k=1}^{N} \frac{1}{2} (z_{k} + z_{k-1}) A_{k}}{\sum_{k=1}^{N} A_{k}} = \frac{\sum_{k=1}^{N} \frac{1}{2} (z_{k} + z_{k-1}) t_{k} n_{k}}{\sum_{k=1}^{N} t_{k} n_{k}}$$
(2)



Fig. 1. Portion of a laminate subjected to a shear force, *P*, and the resulting normal stress distribution on an arbitrary cross-section.



Fig. 2. Original (actual) and transformed laminate cross-sections.

where A_k and t_k are the area and thickness of layer k, respectively. The distance of a point from the neutral axis is denoted by $\hat{z} = z - z^*$.

The applied shear loading causes a normal stress distribution at an arbitrary vertical cross-section given according to beam theory (Beer and Johnston, 1981) by,

$$\sigma_x = -\frac{M\hat{z}}{I} \tag{3}$$

where I is the moment of inertia of the transformed laminate cross-section (Fig. 2) and M is moment at the vertical cross-section. Because a counter clockwise moment is considered positive, equilibrium dictates that M = -Px, thus,

$$\sigma_x = \frac{Px\hat{z}}{I} \tag{4}$$

To obtain the shear force, denoted by *H*, acting on an arbitrary horizontal cross-section at location $\hat{z} = \hat{z}_c$, within ply number *k* (see Fig. 3), consider the equilibrium of forces in the *x*-direction, which requires,

$$-H + \int \sigma_x \, dA = 0 \tag{5}$$

where dA is the area of the differential element indicated in Fig. 3. Note that the positive H sign convention indicated in Fig. 3 is consistent with that employed by Beer and Johnston⁵, see Appendix B. Substituting Eq. (4) into Eq. (5) yields,

$$H = \frac{Px}{I} \int_{\hat{z}_N}^{\hat{z}_c} \hat{z} dA$$
(6)

where $c = \hat{z}_N$ denotes the distance from the neutral axis to the top surface of the laminate (see Fig. 3). Using $dA = b n_k d\hat{z}$, we obtain,

$$H = \frac{Px}{I} \int_{\hat{z}_N}^{z_c} b n_k \, \hat{z} \, d\hat{z} \tag{7}$$



Fig. 3. Section of laminate acted upon by the horizontal shear force, H, and the distributed normal stress, σ_x .

The integral appearing in Eq. (7), which is denoted by $Q'(k,\hat{z})$, can be decomposed as follows,

$$Q'(k,\hat{z}) = \int_{\hat{z}_N}^{\hat{z}_c} b \, n_k \, \hat{z} \, d\hat{z} = \int_{\hat{z}_k}^{\hat{z}_c} b \, n_k \, \hat{z} \, d\hat{z} + \int_{\hat{z}_{k+1}}^{\hat{z}_k} b \, n_{k+1} \, \hat{z} \, d\hat{z} + \dots + \int_{\hat{z}_N}^{\hat{z}_{N-1}} b \, n_N \, \hat{z} \, d\hat{z} \tag{8}$$

It follows that

$$Q'(k,\hat{z}) = \frac{b n_k}{2} \left(\hat{z}_c^2 - \hat{z}_k^2 \right) + \frac{1}{2} \sum_{m=k+1}^N b n_m \left(\hat{z}_{m-1}^2 - \hat{z}_m^2 \right)$$
(9)

where $\hat{z}_N = c$. Hence, the shear force, H, is given by,

$$H = \frac{Px}{I}Q'(k, \hat{z}) \tag{10}$$

The shear stress, au , is given by,

$$\tau = -\frac{H}{xb} \tag{11}$$

where the negative sign is due to the opposite directionality of the internal shear force compared to the shear stress (see Appendix B). The applied shear resultant, Q, is related to the applied shear force, P, by Q = P/b, and it follows that,

$$\tau(k,\hat{z}) = -\frac{Q}{I} Q'(k,\hat{z})$$
⁽¹²⁾

In employing this equation, the moment of inertia of the transformed beam cross-section is given by,

$$I = \sum_{k=1}^{N} \left[\frac{1}{12} b n_k t_k^3 + b n_k t_k \left(\frac{\hat{z}_k + \hat{z}_{k-1}}{2} \right)^2 \right]$$
(13)

Thus, given Eqs. (9) and (13), the shear stress distribution throughout the laminate can be determined from Eq. (12).

It should be emphasized that at the top and bottom of the laminate the shear stress must be equal to zero. In addition, the integral of τ over the entire thickness of the laminate must be equal to the applied shear resultant, Q, that is,

$$\int_{z_0}^{z_N} \tau \, dz = Q \tag{14}$$

III. Verification Cases

In order to verify the analytical formulation, we compare to results from the Higher-Order Theory for Functionally Graded Materials (HOTFGM)¹. The 2D HOTFGM problem domain considered consists of 20×200 subcells in the *z*- and *x*-directions, respectively, subjected to shear loading as shown in Fig. 4. It should be noted that the shear stresses shown in the results below were taken at x = 5 (middle of the domain) in order to ensure that the edge effects do not influence the results. Furthermore, comparison has been made to the HyperSizer Joints² software, which is based on a cylindrical bending plate theory for adhesively bonded laminates.

HOTFGM is a plane strain program, such that $\varepsilon_y = 0$. In the results cases 1 - 5, the Poisson ratios of the layers were assumed to be (nearly) identical, thus the plane strain condition coincides with the plane stress condition. In case 6, the effect of different layer Poisson ratios will be shown.



Fig. 4. HOTFGM representation of the laminate considered.

A. Case 1: Monolithic Material

In the case of a monolithic material, the shear stress distribution reduces to the beam theory parabolic expression. In this case, N = 1, the neutral axis is at the midplane (i.e., $z^* = 0$), $\hat{z}_0 = c$, and $\hat{z}_1 = -c$, see Fig. 5. Therefore, from Eq. (9),

$$Q' = \frac{b}{2} \left(\hat{z}^2 - c^2 \right)$$
 (15)

Since the cross-sectional area A = 2bc, $I = b(2c)^3/12$, and Q = P/b, it follows that

$$\tau = \frac{3P}{2A} \left(1 - \frac{\hat{z}^2}{c^2} \right) \tag{16}$$



Fig. 5. Monolithic (single layer) laminate.

which is the well-known shear stress distribution in a monolithic rectangular beam.

The simplified shear solution (as implemented in FORTRAN) is compared with the HOTFGM solution and the HyperSizer Joints solution for the shear distribution in the monolithic material in Fig. 6. The three methods are in excellent agreement.

B. Case 2: Bi-Material (Stiffer on Top)

The results for this case are shown in Fig. 7. The resulting shear distribution is piece-wise parabolic with the peak occurring in the stiffer material at the location of the neutral axis ($z^* = 0.15$). The results of the simplified shear solution, HOTFGM, and HyperSizer Joints coincide.



Fig. 6. Monolithic material shear stress distribution (Case 1).



Fig. 7. Bi-material laminate shear stress distribution (Case 2).

C. Case 3: Bi-Material (Stiffer on Bottom)

The results for this case are shown in Fig. 8. As in Case 2, the resulting shear distribution is piece-wise parabolic with the peak occurring in the stiffer material at the location of the neutral axis ($z^* = -0.15$). The results of the simplified shear solution, HOTFGM, and HyperSizer Joints are in excellent agreement.

D. Case 4: Three Layers

The results for this case are shown in Fig. 9. Because the laminate is symmetric, the shear distribution is symmetric as well, with maximum at the laminate midplane. The results of the simplified shear solution, HOTFGM, and HyperSizer Joints are in excellent agreement.

E. Case 5: Four Layers

The results for the four layer case are shown in Fig. 10. The peak occurs in the lower half of the laminate, which contains the stiffer materials. The results of the simplified shear solution, HOTFGM, and HyperSizer Joints are in excellent agreement.

F. Case 6: Two Layers - Different Poisson Ratio's

This case is identical to Case 3 except that the Poisson ratios of the layers have been changed. The bottom (stiffer) layer is given a Poisson ratio = 0.45, while the top (more compliant) layer is given a Poisson ratio = 0.05. The results shown in Fig. 11 indicate that the Poisson ratio mismatch causes a slight shifting of the shear stress distribution and amplification of the maximum compared to the Case 3 results, which employed equal Poisson ratios. The simplified shear solution, HOTFGM, and HyperSizer Joints coincide.



Fig. 8. Bi-material laminate shear stress distribution (Case 3).



Fig. 9. Three layer laminate shear stress distribution (Case 4).

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Fig. 10. Four layer laminate shear stress distribution (Case 5).



Fig. 11. Two layers (stiffer on bottom) results for different layer Poisson ratios (Case 6).

In conclusion, it has been demonstrated that the present simplified shear solution coincides with the HOTFGM and HyperSizer Joints predictions for all of the above cases considered.

G. Cases 7 – 9: Comparison with Plate Theory

Here we compare to results from Williams' multilength scale plate theory³, which has been shown to coincide with Pagano's⁶ exact solution for plates in cylindrical bending, as well as HyperSizer Joints. It should be noted that Williams' plate theory³ considers sinusoidal pressure loading on the top of the plate as opposed to an applied shear load. The τ_{xz} distribution from a cross-section within the plate theory results were then integrated obtain the applied Q_x used in the current simplified shear solution. This therefore mimics the HyperSizer situation where a Q_x value is given for a point in the laminate with no knowledge of the global problem or boundary conditions used to generate the Q_x load. In all three cases below, $Q_x = 0.32$ N/mm. We consider three asymmetric laminates, a cross-ply, a [0°/90°/45°/90°/0°], and a [-30°/90°/45°/60°/30°], where the asymmetry arises due to different ply thicknesses, which are [0.2, 0.4, 0.2, 0.1, 0.1] mm for all three laminates. The material properties of the plies are given in Table 1, where the standard expression for v_{yx} is given in Eq. (30). The resulting shear stress distributions for these laminates are shown in Figs. 12 - 14, respectively.

Figure 12 shows that the shear stresses predicted for the cross-ply laminate coincide with the HyperSizer Joints solution, but deviate slightly from Williams' solution³. Figure 13 shows that introducing a 45° ply results in some deviation in the top 90° and 45° plies. Introducing angle plies to the laminate configuration results in the distribution shown in Fig. 14. In conclusion, the simplified shear solution appears to give a good estimate of the shear distributions for the laminates considered, given the method's simplicity and efficiency.

Table 1. Material properties for simplified shear solution comparison with plate theory.

Ply Angle (°)	-30	0	30	45	60	90
E _x (GPa)	2.192	25	2.192	1.325	1.068	1
E _y (GPa)	1.068	1	1.068	1.325	2.192	25
v _{xv}	0.4082	0.25	0.4082	0.3245	0.1989	0.01



Fig. 12. Shear stress distribution for [0°/90°/0°/90°/0°] laminate with ply thickness of [0.2, 0.4, 0.2, 0.1, 0.1] mm (Case 7).



Fig. 13. Shear stress distribution for $[0^{\circ}/90^{\circ}/45^{\circ}/90^{\circ}/0^{\circ}]$ laminate with ply thickness of [0.2, 0.4, 0.2, 0.1, 0.1] mm (Case 8).



Fig. 14. Shear stress distribution for [-30°/90°/45°/60°/30°] laminate with ply thickness of [0.2, 0.4, 0.2, 0.1, 0.1] mm (Case 9).

IV. Design Examples

In order to design a composite laminate or stiffened panel that is subjected to external loading, the first step is to determine the induced local stresses in the structure. Then these stresses are compared to allowable stresses in order to determine the margin of safety of the considered composite panel. The propose simplified shear solution returns ply-level shear stresses at any point in the panel in global x, y, z laminate coordinates (see Fig. 4). However, most failure analysis methods require stress allowables in terms of ply local (x_1, x_2, x_3) coordinates, where $x_3 = z$ and x_1 corresponds to the ply fiber direction. Therefore, stresses in global coordinates obtained from the present analysis for any ply must be transformed into local ply coordinates according to:

$$\begin{cases} \tau_{13} \\ \tau_{23} \end{cases} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{cases} \tau_{xz} \\ \tau_{yz} \end{cases}$$
(17)

where θ is the ply angle (between the fiber direction and the global *x*-direction). Note that in the previous sections, the shear stress τ denotes either τ_{xz} , or τ_{yz} , depending on whether the applied shear force resultant Q stands for Q_x or Q_y (respectively).

Once the ply local stresses are known, it is assumed that failure will occur when the following interaction equation is satisfied:

$$\left(\frac{\tau_{13}}{Fsu_{13}}\right)^2 + \left(\frac{\tau_{23}}{Fsu_{23}}\right)^2 = 1$$
(18)

where Fsu_{13} and Fsu_{23} are the ply material shear stress allowables, respectively, which can be found in references such as MIL-HDBK-17. This interaction equation can be written as a margin of safety (see ref. 7) as,

$$MS = \frac{1}{\sqrt{\left(\frac{\tau_{13}}{Fsu_{13}}\right)^2 + \left(\frac{\tau_{23}}{Fsu_{23}}\right)^2}} - 1$$
(19)

where the margin of safety expresses how close to failure is the given panel. Thus, a positive margin of safety indicates that there is no failure for the considered loading, while a negative margin of safety indicates that failure has occurred.

Finally, it should be mentioned that in the presence of combined applied shear loading (Q_x and Q_y), the current analysis is applicable by superimposing the resulting stress distribution induced by each of Q_x and Q_y independently.

A. Design Example 1 - Unstiffened Laminate

This example considers an unstiffened graphite/epoxy laminate subjected to biaxial transverse shear loading ($Q_x = Q_y = 200$ lb/in). This type of loading could result, for example, at the corner of a rectangular panel subjected to uniform pressure loading. A [45°/-45°/0°/90°/45°/-45°/0°]_s layup is considered with uniform ply thicknesses of 0.005 in., thus forming a total thickness of 0.09 in.

Figure 15 shows the resulting ply-by-ply shear stress distributions in the panel in the global coordinates as obtained by the simplified shear solution. Figure 16 shows the ply-by-ply stresses transformed from global coordinates to ply local coordinates. These shear stresses are then used within Eq. (19) to calculate the margin of safety within each ply. Figure 17 shows these ply-by-ply margins of safety. Note that the minimum margin of safety is 0.03 which occurs in both plies 8 and 11. Since the margin of safety is positive but rather small, it can be concluded that the considered laminate is not highly over designed for the imposed loading.

E ₁ (Msi)	E ₂ (Msi)	V ₁₂	Fsu ₁₃ (ksi)	Fsu ₂₃ (ksi)
23.35	1.65	0.32	14.8	5.32

Table 2. Graphite/epoxy ply material properties.



Fig. 15. Shear stress distribution referred to the laminate global coordinate system.

Fig. 16. Shear stress distribution referred to the laminate local coordinate system.

Fig. 17. Margin of safety distribution within the considered laminate.

B. Design Example 2 - Honeycomb Sandwich Panel

This example considers a honeycomb sandwich panel, whose stress distribution is similar to an unstiffened composite laminate, except that the gradient of shear stress takes place almost entirely in the facesheets and is essentially constant across the core. The honeycomb sandwich facesheets considered are identical to the laminate considered in the previous example, with ply material properties given in Table 2. The honeycomb core material properties are given in Table 3, where it should be noted that the in-plane Young's modulus is taken to be extremely low. The shear strengths of the core differ in the *x* and *y* directions and are typical of Hexcell HRH 10 (Nomex/Phenolic) Honeycomb. The thickness of the core is 1.5 in., and the applied loading is given by $Q_x = Q_y = 1000$ lb/in.

The resulting stress distributions are shown in Fig. 18. The total thickness of the sandwich panel is 1.68 in., while the figure shows the distribution in the region 0.7 in. < z < 0.84 in., where z = 0 at the center of the sandwich. The shear stresses rise rapidly in the facesheet and are virtually constant in the core region. Referring to the local coordinates, the corresponding shear stress distributions are shown in Fig. 19. Once again, these local shear stresses are used to determine the margin of safety within the honeycomb sandwich, which is plotted in Fig. 20. As shown, the margins of safety in the relatively weak core (Fsu₁₃ = 0.11 ksi) are negative while margins of safety in the facesheets remain greater than 5. The negative margin of safety in the core indicates that core failure will occur under the applied loading, indicating the need for a stronger or thicker core. Conversely, the high margin of safety in the facesheet region indicates that the facesheet laminate is over designed for the applied shear loading. Note that sandwich panel facesheets are typically designed to carry in-plane loading, which is absent in the present example.

Table 5. Honeycomb core material properties						
$\mathbf{E}_{\mathbf{x}} = \mathbf{E}_{\mathbf{y}} (\mathbf{psi})$	Fsu _{xz} (ksi)	Fsu _{yz} (ksi)				
0.0001	0.225	0.11				

Table 3. Honeycomb core material properties

Fig. 18. Shear stress distribution referred to the sandwich panel global coordinate system.

Fig. 19. Shear stress distribution referred to the sandwich panel local coordinate system.

Fig. 20. Margin of safety distribution within the honeycomb sandwich panel

C. Design Example 3 - I-Stiffened Panel

This example investigates the shear stress distributions in an I-stiffened panel, as shown in Fig. 21. If the shear force is aligned in the direction of the stiffeners (applied Q_x), then the stiffener webs contributed significantly to the transverse shear stiffness of the panel. On the other hand, if the shear force is applied transversely to the stiffeners (applied Q_y), the assumption is that the stiffener webs do not contribute to the shear stiffness of the panel.

Fig. 21. Schematic of an I-stiffened panel.

For the facesheets and flanges of the I-stiffeners, the laminate is treated in the same way as for unstiffened or sandwich panels by determining the Young's modulus and Poisson's Ratio of each ply in the analysis (x or y) direction. For stiffener webs, if aligned with the analysis direction (for example, applied Q_x on an I-Stiffened panel), the effective stiffness of the web is determined by homogenizing the stiffener webs to an equivalent layer stiffness. This homogenization can be approximated by the simple expression:

$$E_x^{eq} = \frac{A_{11,web}^{\mu}}{S_x} = \frac{E_{x,web} t_{web}}{S_x}$$
(20)

where $A_{11,web}^{u}$ is the "uncoupled" A_{11} stiffness term of the web, $E_{x,web}$ is the effective elastic modulus of the web material, t_{web} is the thickness of the web, and S_x is the stiffener spacing. A more extensive discussion of homogenization of the stiffener web can be found in ref. 8.

For shear force applied in the transverse direction (Q_y) , the stiffener web is assumed to be non-existent and the facesheet is treated as an unstiffened laminate. In the case of transverse shear force applied to a stiffened sandwich (such as a blade sandwich or an I-Sandwich, which incorporate bottom facesheets), the stiffener web stiffness is set to an extremely low value (to avoid numerical problems) and the panel is treated similarly to a honeycomb stiffened sandwich. It should be noted that the present simplified shear solution method provides a panel acreage analysis tool that captures interlaminar stresses away from stress concentrations, such as those that occur at free edges.

This example considers a facesheet with ply material properties as given in Table 2. The facesheet layup is, as previously considered, $[45/-45/0/90/0/90/45/-45/0]_s$, with ply thicknesses of 0.005 in. thus forming a total thickness of 0.09 in. The upper flange and web of the I-stiffeners consist of $[0/90/45/-45]_s$ laminates with a ply thickness of 0.00375 in., thus forming a total thickness of 0.03 in. As for the lower flange, the layup is $[0/90/45/-45/0/0]_s$, with ply thickness of $[0.005/0.005/0.005/0.005/0.00375/0.00375]_s$ in., thus forming a total thickness of 0.03 in. The applied shear loading is given by $Q_x = Q_y = 200$ lb/in.

Stress profiles at cut A-A, defined in Fig. 22, are shown in Figs. 23 - 25. Figure 23 shows the τ_{xz} and τ_{yz} shear stresses in global coordinates through the entire panel depth. Note that the Q_x load is reacted by the facesheets as well as through the web, resulting in much lower stresses. At the same time, the Q_y load is reacted strictly in the facesheet meaning that the τ_{yz} stresses are much higher. Figure 24 provides a detail of the stresses in the facesheet/flange combination, still in global coordinates. Figure 25 shows ply stresses in ply local coordinates, τ_{13} and τ_{23} . These stresses are used to calculate margins of safety, which are plotted in Fig. 26 for the facesheet. Note that the margins of safety in the I-stiffener have not been plotted as they are very high. The minimum margin of safety is 1.74, indicating that the panel is over designed for the considered loading.

Fig. 22. Location of the cut A-A in the I-stiffened panel.

Fig. 23. Shear stress distribution in the I-stiffened panel at cut A-A referred to panel global coordinates.

Fig. 24. Detail of the shear stress distribution in the I-stiffened panel at cut A-A referred to panel global coordinates.

Fig. 25. Detail of the shear stress distribution in the I-stiffened panel at cut A-A referred to local ply coordinates.

Fig. 26. Margin of safety distribution within the I-stiffened panel facesheet.

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D. Design Example 4 - Unstiffened Laminates in Pressure Shell Structure

This example investigates the use of the simplified shear solution in the design of a complicated structure, in which the loads applied on each component is obtained from a finite element analysis. Subsequently, the structural sizing code HyperSizer⁴ is used to interface with the finite element model of the structure, extract the appropriate component loads, and then size the components based on obtaining all positive margins of safety. The simplified shear solution has been implemented within HyperSizer to provide an additional ply level margin of safety (see Eq. (19)).

The structural components considered are the 14 unstiffened laminate panels within a spacecraft pressure shell. The composite material considered is a woven graphite/epoxy laminate, whose ply material properties, which are needed by both HyperSizer and the simplified shear solution, are given in Table 3. The ply thickness is 0.008 in., and HyperSizer is used to determine the number of plies (and thus total thickness) needed for each composite component. Furthermore candidate laminates consisting of only 0° and 45° plies in a symmetric layup were considered.

Figure 27 shows the thickness of each component as obtained from HyperSizer without consideration of the simplified shear solution. That is, no check has been made for ply failure vs. the through-thickness shear failure mode. It can be readily seen that most components have sized to a thickness of between 0.16 in. and 0.416 in. (20 to 52 plies). Three components require a thickness of approximately 0.9 in.

The resulting simplified shear solution shear stress fields for one particular component (as indicated by the arrow in Fig. 27) are shown in Fig. 28. As can be observed, the τ_{yz} component is higher than the τ_{xz} component, which is due to the higher Q_y load value for this component that was determined by the finite element solution. As indicated by Table 3, the allowable shear stress (in ply coordinates) is significantly lower (6.9 ksi) than the maximum shear stresses magnitude indicated in Fig. 27 (51.14 ksi). Thus, failure of this component can be expected due to the high value of the induced shear stress. As shown in Fig. 29, when the simplified shear solution failure mode is considered, 11 of the 14 components of the structure are predicted to fail, as indicated by negative margins of safety (red color) in Fig. 29.

E ₁	E ₂	v ₁₂	G ₁₂	Ftu ₁	Ftu ₂	Fsu ₁₂	Fsu ₁₃	Fsu ₂₃
(Msi)	(Msi)		(Msi)	(ksi)	(ksi)	(ksi)	(ksi)	(ksi)
10.5	10.5	0.036	0.84	59	59	13	6.9	6.9

Fig. 27. Unstiffened laminate component thickness (in.), sized without simplified shear solution failure mode.

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Next HyperSizer is permitted to size all laminate components of the structure vs. the simplified shear solution failure mode (in conjunction with all other failure modes). The resulting laminate thicknesses are shown in Fig. 30. This figure shows that much greater thicknesses are required for a closed design (i.e., no negative margins) when the simplified shear solution failure mode is considered (compare to Fig. 27).

Fig. 28. Shear stress distribution within the component indicated by the arrow in Fig. 27.

Fig. 29. Margin of safety of the previously designed composite laminate components.

Fig. 30. Unstiffened laminate component thickness (in.), sized including simplified shear solution failure mode.

V. Conclusion

A simplified theory based on the strength of materials approach has been presented for determination of the shear stress distribution in laminated plates and panels caused by applied shear force resultants. The method is straightforward and does not require the solution of elasticity equations in the presence of the corresponding boundary conditions. As such it provides an estimate of the shear stress distribution with no knowledge of the details of the structure using only panel cross-section geometry, material properties, and the applied load.

The predicted shear stress distribution for laminates are shown to be in excellent agreement with two alternative more complicated solutions, namely HOTFGM¹ and HyperSizer Joints², for isotropic plies. For anisotropic plies, the agreement between the simplified shear solution, HyperSizer Joints², and the exact solution³ is satisfactory given the simplicity and efficiency of presented expressions involved in this method.

Finally, in four design examples, the method has been applied to predict the biaxial shear distributions in an unstiffened laminate, a honeycomb sandwich panel, and I-stiffened panel. The shear stress distributions in the local ply coordinates are obtained by the relevant transformations, enabling determination of the margins of safety of these composite structures.

Appendix A – Plane Strain Effective Young's Modulus Replacement

The fully multi-axial orthotropic normal constitutive equations can be written as,

$$\mathcal{E}_{x} = \frac{1}{E_{x}}\sigma_{x} - \frac{V_{yx}}{E_{y}}\sigma_{y} - \frac{V_{zx}}{E_{z}}\sigma_{z}$$
(21)

$$\mathcal{E}_{y} = -\frac{V_{xy}}{E_{x}}\sigma_{x} + \frac{1}{E_{y}}\sigma_{y} - \frac{V_{zy}}{E_{z}}\sigma_{z}$$
(22)

$$\varepsilon_z = -\frac{v_{xz}}{E_x}\sigma_x - \frac{v_{yz}}{E_y}\sigma_y + \frac{1}{E_z}\sigma_z$$
(23)

In both beam theory and plate theory, the through-thickness stress, σ_z , is assumed to be zero, allowing the Eqs. (21) and (22) to be written as,

$$\varepsilon_x = \frac{1}{E_x} \sigma_x - \frac{V_{yx}}{E_y} \sigma_y \tag{24}$$

$$\varepsilon_{y} = -\frac{\nu_{xy}}{E_{x}}\sigma_{x} + \frac{1}{E_{y}}\sigma_{y}$$
⁽²⁵⁾

In beam theory the *y*-direction assumption is plane stress, $\sigma_y = 0$, leaving for Eq. (24),

$$\varepsilon_x = \frac{1}{E_x} \sigma_x \tag{26}$$

In plate theory, the y-direction assumption is plane strain, $\varepsilon_y = 0$, allowing σ_y to be determined from Eq. (25) as,

$$0 = -\frac{V_{xy}}{E_x}\sigma_x + \frac{1}{E_y}\sigma_y \quad \rightarrow \quad \sigma_y = \frac{E_y}{E_x}v_{xy}\sigma_x \tag{27}$$

Substituting Eq. (27) into Eq. (24) gives,

$$\varepsilon_{x} = \frac{1}{E_{x}}\sigma_{x} - \frac{V_{yx}}{E_{y}} \left[\frac{E_{y}}{E_{x}} V_{xy} \sigma_{x} \right] \longrightarrow \qquad \varepsilon_{x} = \frac{1 - V_{xy} V_{yx}}{E_{x}} \sigma_{x}$$
(28)

Comparing Eq. (28) to Eq. (26), we see that the correct substitution in going from plane stress (beam theory) to plane strain (plate theory) is,

$$E_x \rightarrow \frac{E_x}{1 - v_{xy} v_{yx}}$$
 (29)

Also, noting that,

$$V_{yx} = \frac{E_y}{E_x} V_{xy}$$
(30)

we have,

$$E_x \rightarrow \frac{E_x}{1 - \frac{E_y}{E_x} (v_{xy})^2}$$
 (31)

Appendix B - Shear Sign Convention

The sign convention for positive external shear loading is shown in Fig. B.1. This is consistent with Eq. (4),

Fig. B.1. Positive sign convention for external shear loading on a beam.

$$\sigma_x = \frac{Pxz}{I} \tag{32}$$

which indicates negative (compressive) normal stress in the beam for a positive shear load (P) in the lower half of the beam (z < 0). The sign convention for the internal shear force (V) in the beam, which corresponds to the sign convention employed by Beer and Johnston⁵, is shown in Fig. B.2. As shown, the reaction shear force (R) at x = L is equal to P, while, due to equilibrium, the internal shear force in the beam, V = -P. Taking a horizontal cut of one of the portions of the beam, it is clear that the indicated sign convention for the directionality of the internal horizontal shear force (H) is consistent with the vertical shear force (V) sign convention. Considering an infinitesimal element of the beam along the face of the horizontal cut, it is clear that the standard sign convention for the internal shear stress is opposite of that employed for the internal shear forces. This is the motivation for the negative sign in Eq. (11), which then enables a positive applied shear force P to result in a positive internal shear stress distribution.

Fig. B.2. Positive sign convention for internal shear force and shear stress in a beam.

²⁴ American Institute of Aeronautics and Astronautics

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